

MAMBA UNIVERSAL WIRING GUIDE



MAMBA MK4 H743 V2

Mobile WIFI Reference use tutorial

1、SpeedyBee APP, WIFI, WIF"Mamba Stack"

Open SpeedyBee APP and connect your FC with WIFI. The WIFI name is "Mamba Stack".

If your current model is not in the list, simply select any of the diaotne models

2、UART4 MSP

Ensure that the port UART4 MSP setting is on (factory default on)

Download URL: www.speedybee.com/download/



SpeedyBee APP

Download



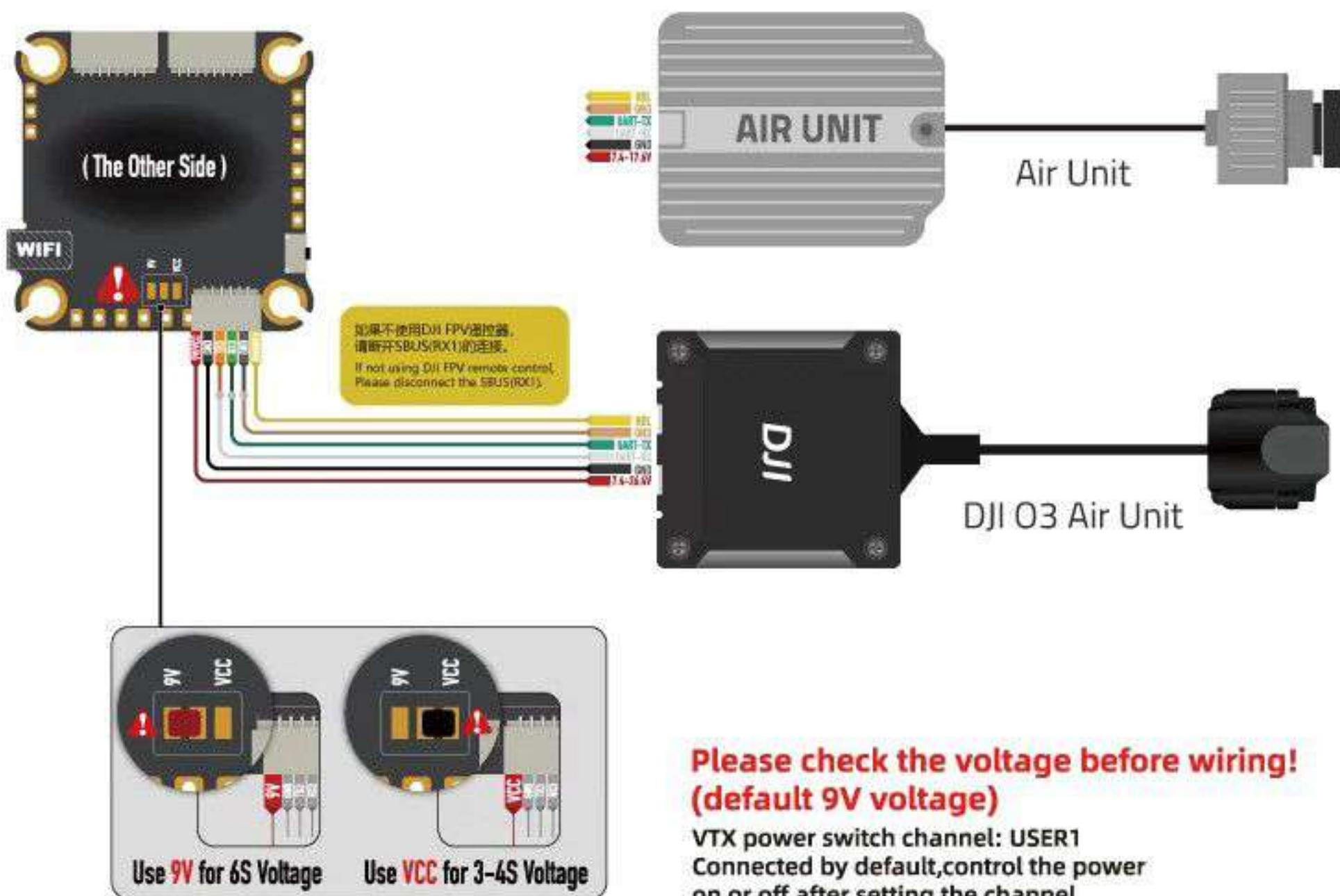
| Identifier | Configuration/MSP | Serial RX |
|------------|--|-------------------------------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 ▼ | <input type="checkbox"/> |
| UART 1 | <input type="checkbox"/> 115200 ▼ | <input checked="" type="checkbox"/> |
| UART 2 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> |
| UART 3 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> |
| UART 4 | <input checked="" type="checkbox"/> 115200 ▼ | <input type="checkbox"/> |
| UART 5 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> |

Attention:

1. If you don't see your FC in the connection list, please wait for the official Speedybee update.
2. If you are connected to WIFI and are prompted with "Connecting" or "MSP not responding", please check the settings in "Ports-UART4". Keep the Speedybee APP in the latest version, restart the device and the Speedybee APP.

DJI Wiring

| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
|------------|--|-------------------------------------|-------------------|-------------------|-------------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 1 | <input type="checkbox"/> 115200 ▼ | <input checked="" type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 2 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 3 | <input checked="" type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 4 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 5 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 6 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |

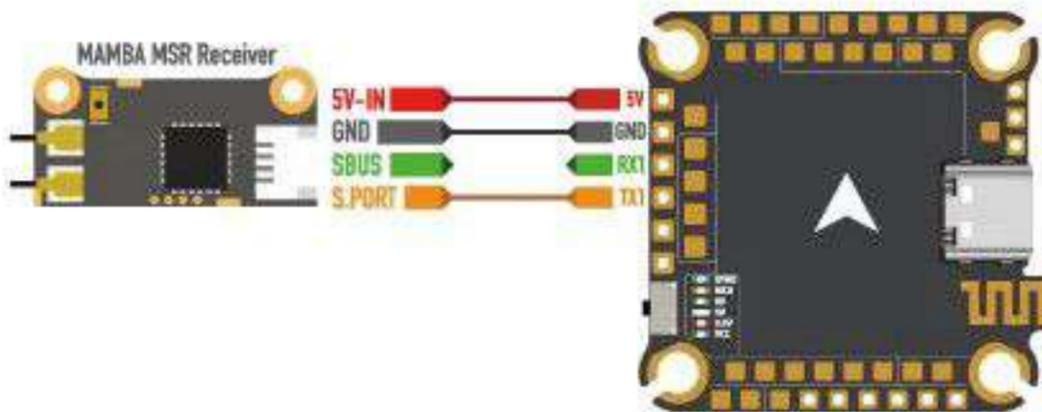


Correspond USER1 to the AUX channel of the remote control.(As shown in the following figure)



MAMBA MSR Receiver (F.Prot) Wiring

| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
|------------|--|-------------------------------------|------------------|---------------|---------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 1 | <input type="checkbox"/> 115200 | <input checked="" type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 2 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 3 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 4 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 5 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 6 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |



Receiver

Serial-based receiver (SPEKSAY,£) Receiver Mode

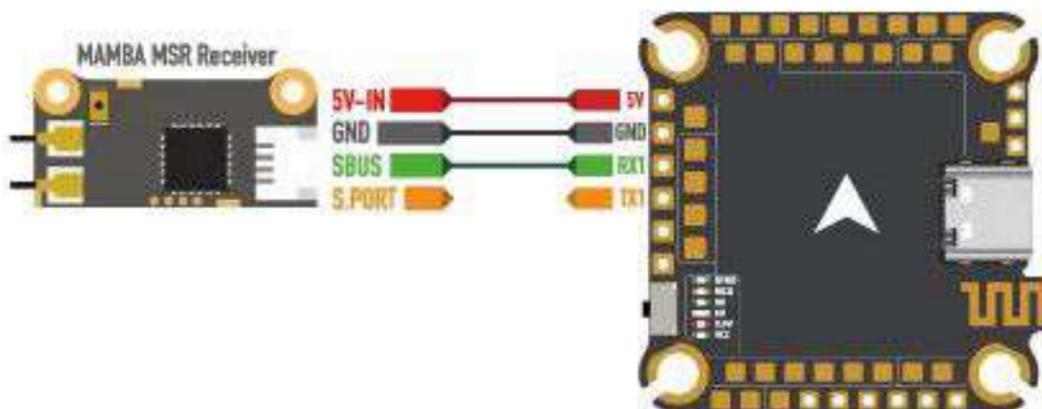
Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

FrSky FPort Serial Receiver Provider

TELEMETRY Telemetry output

MAMBA MSR Receiver (SBUS) Wiring

| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
|------------|--|-------------------------------------|------------------|---------------|---------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 1 | <input type="checkbox"/> 115200 | <input checked="" type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 2 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 3 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 4 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 5 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |
| UART 6 | <input type="checkbox"/> 115200 | <input type="checkbox"/> | Disabled AUTO | Disabled AUTO | Disabled AUTO |



Receiver

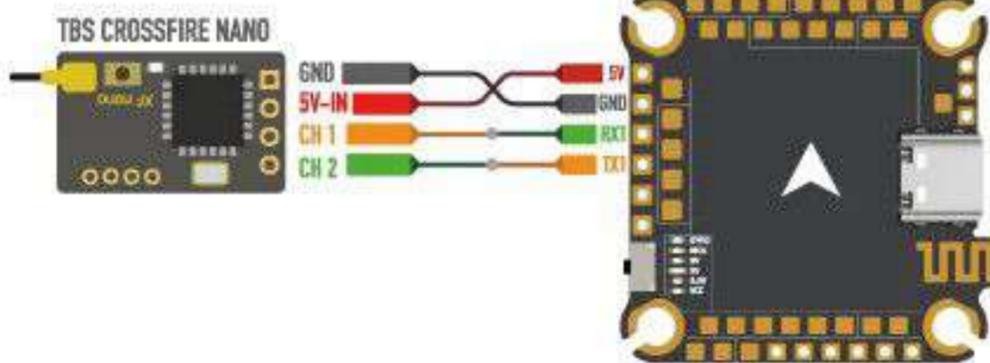
Serial-based receiver (SPEKSAY,£) Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

SBUS Serial Receiver Provider

TBS CROSSFIRE NANO Wiring

| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
|------------|--|-------------------------------------|-------------------|-------------------|-------------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 1 | <input type="checkbox"/> 115200 ▼ | <input checked="" type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 2 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 3 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 4 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 5 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 6 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |



Receiver

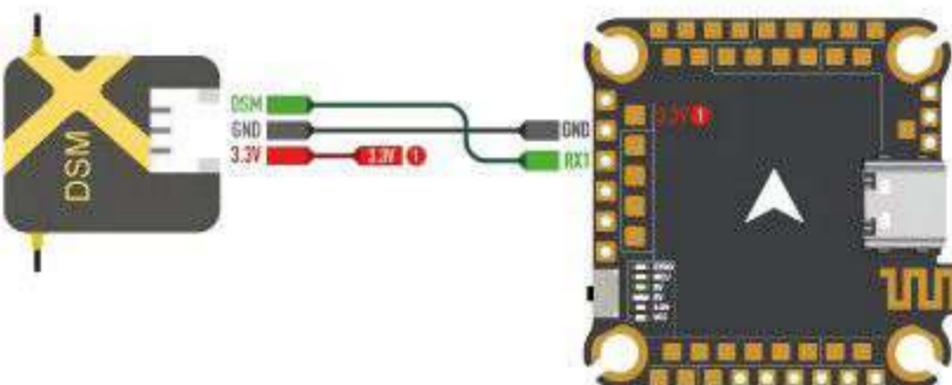
Serial-based receiver (SPEKSAY,ε) Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

CRSF Serial Receiver Provider

DSM Wiring

| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
|------------|--|-------------------------------------|-------------------|-------------------|-------------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 1 | <input type="checkbox"/> 115200 ▼ | <input checked="" type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 2 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 3 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 4 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 5 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 6 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |



DSM接收机需要按步骤操作

1. 选择DSMX 协议; ([SPEKTRUM1024](#)或[SPEKTRUM2048](#))
2. betaflight设置;
cli命令输入:[set spektrum_sat_bind = 5 save](#)
3. 对频操作;
4. 接收机对频完成后, betaflight设置;
cli命令输入:[set spektrum_sat_bind = 0 save](#)
5. 完成;

DSM receivers need to follow the steps

1. Select DSMX protocol ([SPEKTRUM1024](#) or [SPEKTRUM2048](#))
2. betaflight settings:
cli command line input:[set spektrum_sat_bind = 5 save](#)
3. Frequency pairing operation.
4. After the receiver completes the frequency pairing, set betaflight
cli command line input:[set spektrum_sat_bind = 0 save](#)
5. Finish

Receiver

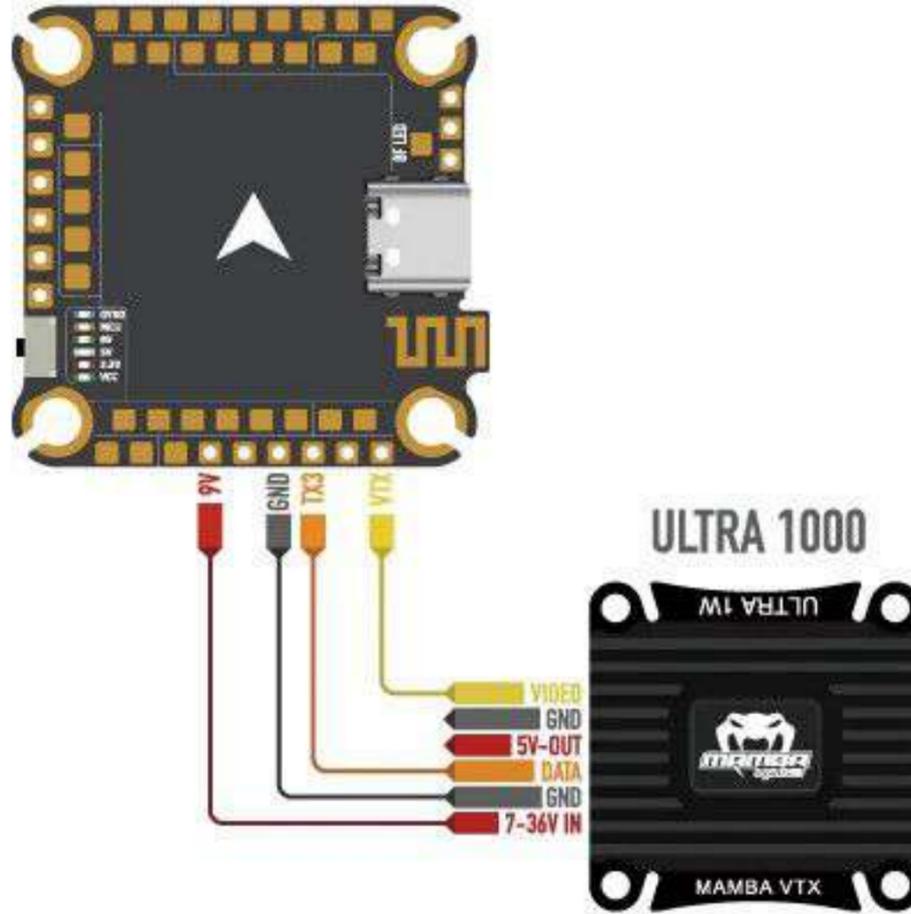
Serial-based receiver (SPEKSAY,ε) Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

SPEKTRUM2048 Serial Receiver Provider

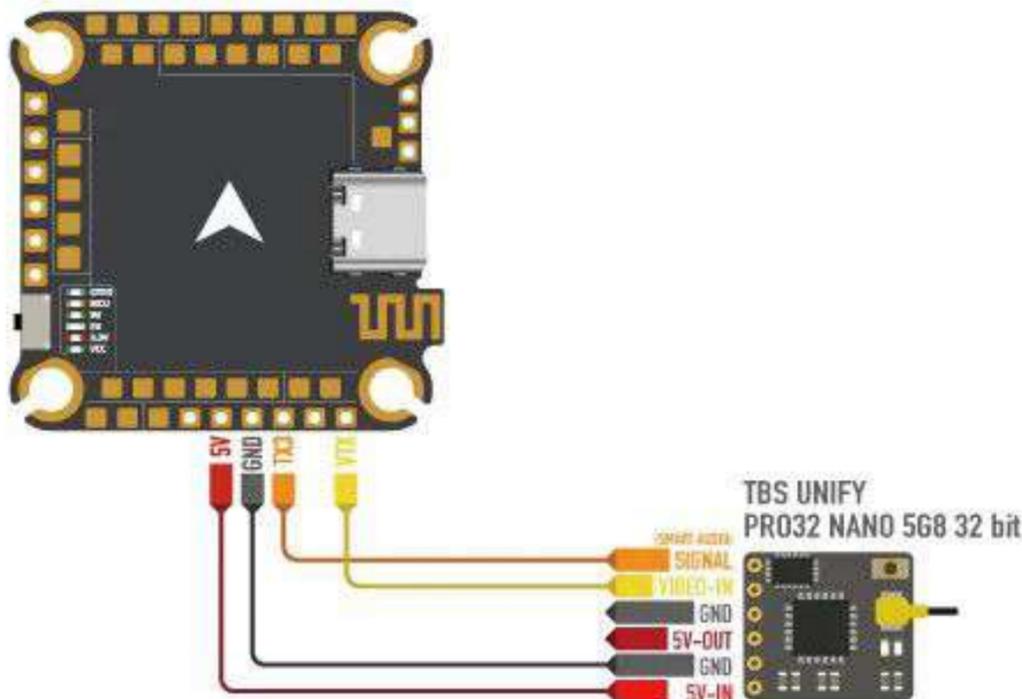
MAMBA ULTRA 1000 Video Transmitter Wiring

| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
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| UART 1 | <input type="checkbox"/> 115200 ▼ | <input checked="" type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 2 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 3 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | VTX(IRC Tran ▼ AUTO ▼ |
| UART 4 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 5 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 6 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | GPS ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |



TBS UNIFY PRO32 NANO 5G8 32 bit Wiring

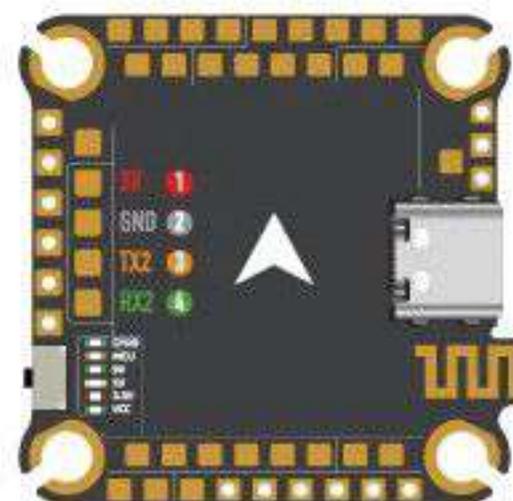
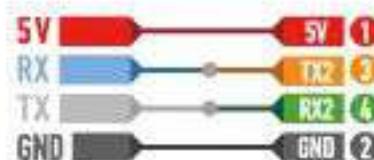
| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
|------------|--|-------------------------------------|-------------------|-------------------|----------------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 1 | <input type="checkbox"/> 115200 ▼ | <input checked="" type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 2 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 3 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | VTX(TBS Sma ▼ AUTO ▼ |
| UART 4 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 5 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |
| UART 6 | <input type="checkbox"/> 115200 ▼ | <input type="checkbox"/> | Disabled ▼ AUTO ▼ | GPS ▼ AUTO ▼ | Disabled ▼ AUTO ▼ |



MAMBA M22/M8 PLUS GPS Wiring

| Identifier | Configuration/MSP | Serial RX | Telemetry Output | Sensor Input | Peripherals |
|------------|--|--------------------------|-------------------|---------------------|-------------------|
| USB VCP | <input checked="" type="checkbox"/> 115200 ▾ | <input type="checkbox"/> | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ |
| UART 1 | <input type="checkbox"/> 115200 ▾ | <input type="checkbox"/> | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ |
| UART 2 | <input type="checkbox"/> 115200 ▾ | <input type="checkbox"/> | Disabled ▾ AUTO ▾ | GPS ▾ AUTO ▾ | Disabled ▾ AUTO ▾ |
| UART 3 | <input type="checkbox"/> 115200 ▾ | <input type="checkbox"/> | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ |
| UART 4 | <input type="checkbox"/> 115200 ▾ | <input type="checkbox"/> | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ |
| UART 5 | <input type="checkbox"/> 115200 ▾ | <input type="checkbox"/> | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ |
| UART 6 | <input type="checkbox"/> 115200 ▾ | <input type="checkbox"/> | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ | Disabled ▾ AUTO ▾ |

- Setup
- Ports
- Configuration**
- Power & Battery
- PID Tuning
- Receiver
- Modes
- Modes
- OSD
- Video Transmitter
- LED Strip
- Blackbox
- CLI



GPS

GPS GPS for navigation and telemetry

Note: Remember to configure a Serial Port (via Ports tab) when using GPS feature.

NMEA ▾ Protocol

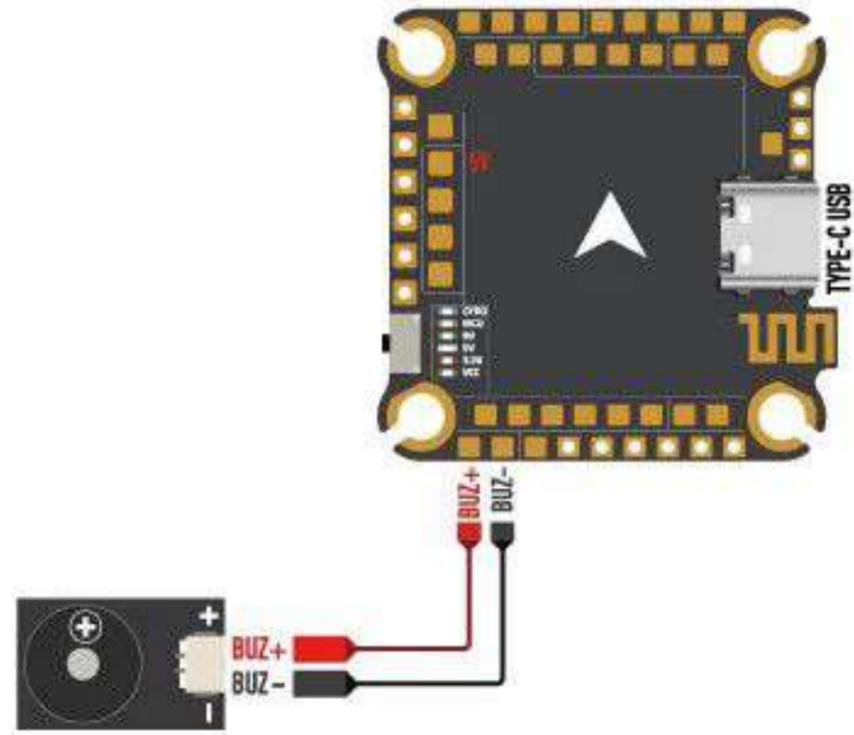
Auto Baud

Auto Config

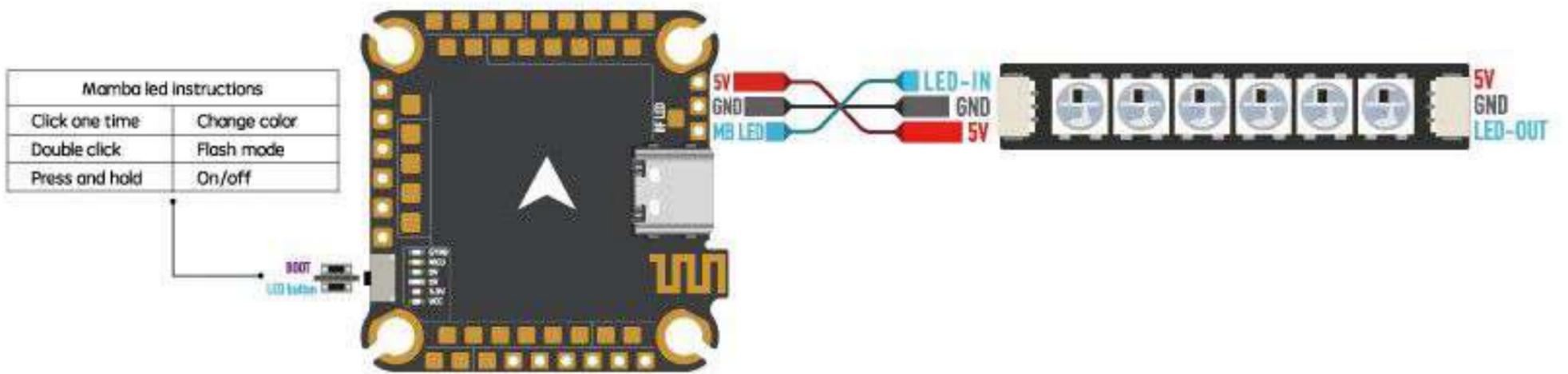
Auto-detect ▾ Ground Assistance Type

0.00 ▾ Magnetometer Declination(deg)

BUZZER Wiring



LED Wiring



Camera Wiring

